

FIG. 1



$$T_{driver} = T_{desired} - T_{delay}$$

FIG. 2

FIS920030233US1
2/3



$$T_{receive} = T_{measure} + T_{delay}$$

FIG. 3

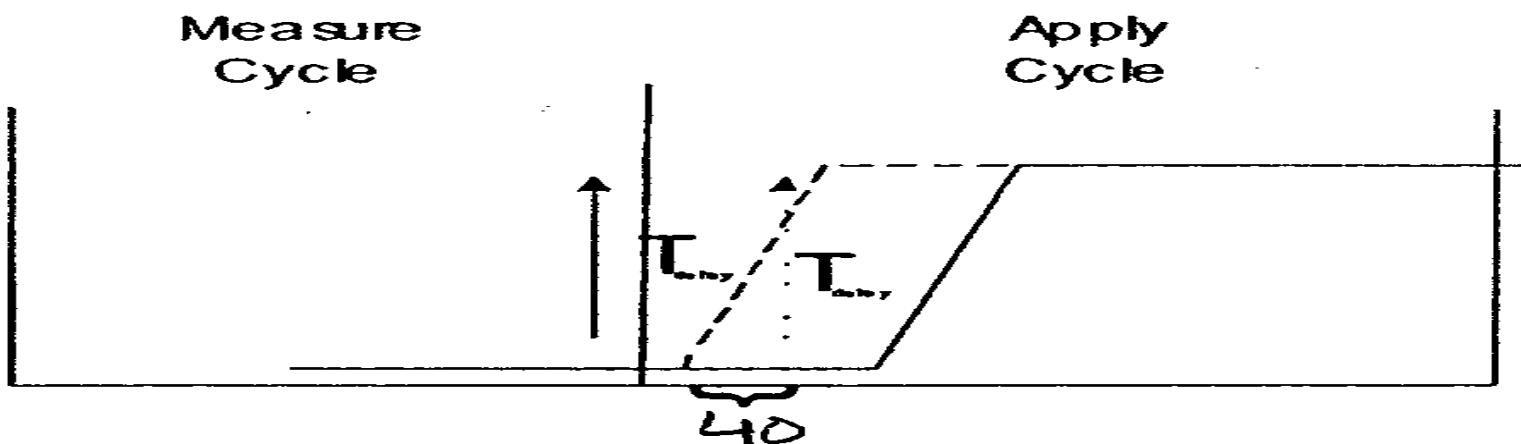
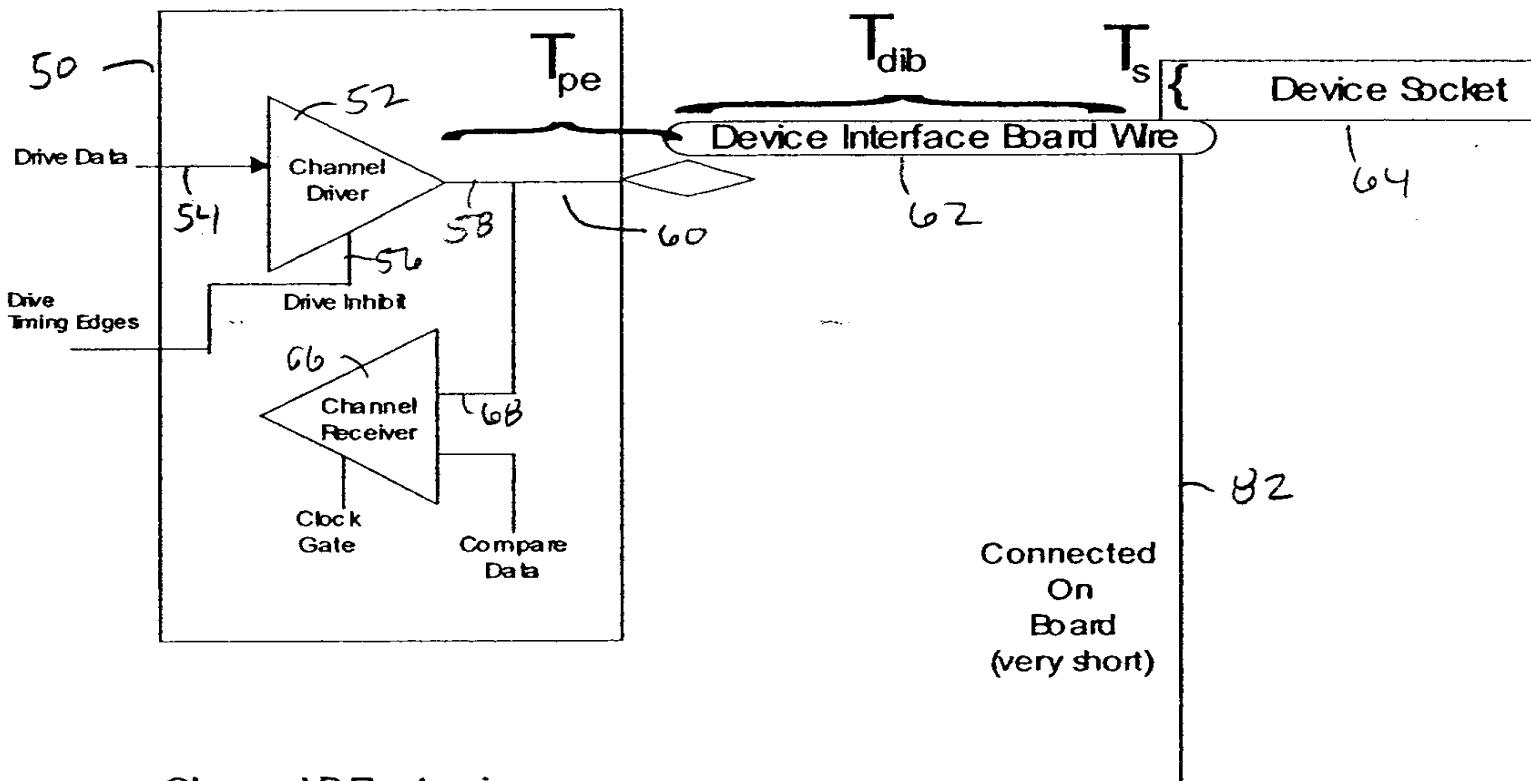


FIG. 4

Channel A Electronics



Channel B Electronics

